

# INTEL<sup>®</sup> DISTRIBUTION OF OPENVINO<sup>™</sup> TOOLKIT

# Accelerate Computer Vision with OpenVINO<sup>™</sup> toolkit

(Open Visual Inference & Neural Network Optimization) - Formerly Intel® Computer Vision SDK

### What it is

A toolkit to fast-track development of **high performance computer vision** and **deep learning into vision applications**. It enables deep learning on hardware accelerators and easy **heterogeneous** execution across Intel<sup>®</sup> platforms. Components include:

- Intel<sup>®</sup> Deep Learning Deployment Toolkit (model optimizer, inference engine)
- Optimized functions for OpenCV\*, media encode/decode, and more

### Why important

Demand is growing for intelligent vision solutions. **Deep learning revenue** is estimated to grow from \$655M in 2016 to **\$35B by 2025**<sup>1</sup>. This requires **developer tools** to integrate computer vision, deep learning, and analytics processing capabilities into applications, so they can help **turn data into insights that fuel artificial intelligence**.

#### Users

Software developers, data scientists working on vision solutions for surveillance, robotics, healthcare, office automation, transportation, & more.



OpenVINO<sup>™</sup> version is 2018 R2 <sup>1</sup>Tractica 2Q 2017

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Free Download ► software.intel.com/openvino-toolkit

(intel)

# What's Inside the OpenVINO<sup>™</sup> toolkit



OS Support CentOS\* 7.4 (64 bit) Ubuntu\* 16.04.3 LTS (64 bit) Microsoft Windows\* 10 (64 bit) Yocto Project\* version Poky Jethro v2.0.3 (64 bit)



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# Benefits of the OpenVINO<sup>™</sup> toolkit

Harness the Power of Intel® Processors: CPU, CPU with Integrated Graphics, FPGA, VPU **ACCELERATE PERFORMANCE INTEGRATE DEEP LEARNING** Up to Access Intel computer vision accelerators. Unleash convolutional neural 19.9x Speed code performance. network (CNN) based deep increase Supports heterogeneous processing learning inference & asynchronous execution. using a common API & 20 pre-trained models. SPEED DEVELOPMENT **INNOVATE & CUSTOMIZE** Reduce time using a library of optimized Use the increasing repository OpenCV\* & OpenVX\* functions, & 15+ samples. of OpenCL<sup>™</sup> starting points in OpenCV\* Develop once, deploy for current to add your own unique code. & future Intel-based devices.

<sup>1</sup>Performance increase comparing certain standard framework models vs. Intel-optimized models in the Intel® Deep Learning Deployment Toolkit. See Benchmarks slides for details. Benchmark results were obtained prior to implementation of recent software patches and firmware updates intended to address exploits referred to as "Spectre" and "Meltdown". Implementation of these updates may make these results inapplicable to your device or system. For more complete information about performance and benchmark results, visit <u>www.intel.com/benchmarks</u>.

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# Intel as Best Choice for Vision Solutions

Deliver High Performance Computer Vision & Deep Learning – Transform Data & Results into Artificial Intelligence

### Intel offers the broadest portfolio of hardware and software that help you

- Accelerate workloads for a wide range of solutions and vertical use cases
- Increase application performance through Intel accelerators and flexible heterogeneous architectures<sup>1</sup> (CPU, CPU w/integrated graphics, FPGA, and Vision Processing Units (VPU))
- Drive power, cost and development efficiencies to designs and applications for cameras, gateways, network video recorders (NVR), and servers
- Enable deep learning capabilities for smarter, faster analytics transform data into artificial intelligence for competitive advantage



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# Increase Deep Learning Workload Performance on Public Models using OpenVINO<sup>™</sup> toolkit & Intel<sup>®</sup> Architecture



### Fast Results on Intel Hardware, even before using Accelerators

<sup>1</sup>Depending on workload, quality/resolution for FP16 may be marginally impacted. A performance/quality tradeoff from FP32 to FP16 can affect accuracy; customers are encouraged to experiment to find what works best for their situation. The benchmark results reported in this deck may need to be revised as additional testing is conducted. The results depend on the specific platform configurations and workloads utilized in the testing, and may not be applicable to any particular user's components, computer system or workloads. The results are not necessarily representative of other benchmarks and other benchmark results may show greater or lesser impact from mitigations. For more complete information about performance and benchmark results, visit <u>www.intel.com/benchmarks</u>. Configuration: Intel® Core™ i7-6700K CPU @ 2.90GHz fixed, GPU GT2 @ 1.00GHz fixed Internal ONLY testing, performed 4/10/2018 Test v312.30 – Ubuntu\* 16.04, OpenVINO™ 2018 RC4. Tests were based on various parameters such as model used (these are public), batch size, and other factors. Different models can be accelerated with different Intel hardware solutions, yet use the same Intel software tools. Benchmark Source: Intel Corporation

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### Get an even Bigger Performance Boost with Intel® FPGA

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# Call to Action, Resources

Download ► Free OPENVINO<sup>™</sup> toolkit

### Learn More

Get started quickly with:

- Developer resources
- Intel<sup>®</sup> Tech.Decoded online webinars, tool how-tos & quick tips
- Hands-on in-person events

### Support

 Connect with Intel engineers & computer vision experts at the public <u>Community Forum</u>

Select Intel customers may contact their Intel representative for issues beyond forum support.





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# Activity 1: Setup Intel<sup>®</sup> Distribution of openVINO<sup>™</sup> toolkit (openVINO)

Setup openVINO:

source /opt/intel/openvino/bin/setupvars.sh

Run Classification demo using SqueezeNet:

cd /opt/intel/openvino/deployment tools/demo/

sudo ./demo\_squeezenet\_download\_convert\_run.sh

Run Security Barrier Camera Demo:

sudo ./demo\_security\_barrier\_camera.sh



# Activity 2: Model Optimizer

# Download VGG\_16

cd /opt/intel/openvino/\
deployment\_tools/tools/model\_downloader/

./downloader.py --name vgg16 -o ~/lab5

## Convert and Optimize model:

cd /opt/intel/openvino/deployment\_tools/model\_optimizer/

python36 mo.py --input\_model ~/lab5/\
classification/vgg/16/caffe/vgg16.caffemodel \--output\_dir ~/lab5/IR/ -reverse\_input\_channels -b 1

# **Activity 3: Classification**

# Run classification with VGG16:

cd ~/inference\_engine\_samples\_build/intel64/Release

./classification\_sample \
-i ~/lab5/input\_files/cat.jpg \
-m ~/lab5/IR/vgg16.xml



# Activity 4: Object detection

## Download model

cd /opt/intel/openvino/\
deployment\_tools/tools/model\_downloader/

./downloader.py --name ssd mobilenet v2 coco -o ~/lab5/

### Convert and Optimize TensorFlow\* model:

cd /opt/intel/openvino/deployment\_tools/model\_optimizer/

./mo\_tf.py --input\_model ~/lab5/object\_detection/common/\
ssd\_mobilenet\_v2\_coco/tf/ssd\_mobilenet\_v2\_coco.frozen.pb \
--output\_dir ~/lab5/IR/ --reverse\_input\_channels \
--tensorflow\_use\_custom\_operations\_config "extensions/front/tf/ssd\_support.json" \
--tensorflow\_object\_detection\_api\_pipeline\_config ~/lab5/tf\_model/pipeline.config

# Activity 4.1: Run video

# Object detection with openVINO:

cd ~/inference\_engine\_samples\_build/intel64/Release/

./object\_detection\_demo\_ssd\_async \
-i ~/lab5/input\_files/denver.mp4 \
-m ~/lab5/IR/ssd\_mobilenet\_v2\_coco.frozen.xml -t 0.6



# Activity 5: VNNI

# Download models:

```
cd /opt/intel/\
```

openvino/deployment\_tools/tools/model\_downloader/

# Download FP32:

./downloader.py --name vehicle-\
attributes-recognition-barrier-0039 -o ~/lab6/

# Download INT8:

```
./downloader.py --name vehicle-\
attributes-recognition-barrier-0039-int8 -o ~/lab6/
```



# Activity 5.1: VNNI

### Benchmak:

cd ~/inference\_engine\_samples\_build/intel64/Release/ Download FP32:

./benchmark\_app -m ~/lab6/Security/object\_attributes/vehicle/\
resnet10\_update\_1/dldt/\
vehicle-attributes-recognition-barrier-0039.xml -i /opt/\
intel/openvino/deployment\_tools/demo/car.png

### **Download INT8:**

./benchmark\_app -m ~/lab6/Security/object\_attributes/vehicle/\
resnet10\_update\_1/dldt/\
vehicle-attributes-recognition-barrier-0039-int8.xml -i /opt/\
intel/openvino/deployment\_tools/demo/car.png



Software